

*Patent*

UNITED STATES PATENT APPLICATION  
FOR  
**METHOD AND APPARATUS FOR EXECUTION FLOW SYNONYMS**

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ATTORNEY'S DOCKET NO. 42P17885

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"Express Mail" mailing label number: EV305339385US

Date of Deposit: December 10, 2003

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## **METHOD AND APPARATUS FOR EXECUTION FLOW SYNONYMS**

### **FIELD**

[0001] The present disclosure relates generally to microprocessors,  
5 and more specifically to microprocessors including several execution  
units of differing types.

### **BACKGROUND**

[0002] Modern microprocessors may support the execution of  
complex instructions by converting them into a group of simpler  
10 instructions. The resulting group of simpler instructions may be called  
a "flow". There may be flows consisting of micro-operations and  
described by microcode. These flows may be called microcode flows.  
There may also be flows whose conversion into a group of simpler  
instructions may be performed by a set of hardware logic. These flows  
15 may be called hardware flows. A processor may first decode the  
instruction into a microcode flow or a hardware flow, and then schedule  
the resulting microcode flow for execution on one or more execution  
units.

[0003] The execution units of a processor may be of varying types.  
20 For example, one processor may include one or more of the following  
types of execution units in its architecture: integer arithmetic, floating-  
point arithmetic, multimedia arithmetic, branch calculations and  
control; and memory load/store. Generally a microcode flow or a  
hardware flow representation of an instruction will be targeted to  
25 execute on one of these types of execution unit. However, often the  
targeted execution unit is not available or at least less available than  
others. The reason it may be not available or less available may be as

simple as that execution unit is currently executing another flow corresponding to another instruction. But in some cases the targeted execution unit may be less available because it is turned off as a result of the processor entering a reduced power mode. To execute the

5 microcode flow or hardware flow, the processor must first emerge from such a reduced power mode. In some cases, the targeted execution unit may be less available or not available due to a soft or hard failure.

Each of these situations raises issues for the execution of the microcode flow or hardware flow representation of the instruction.

**BRIEF DESCRIPTION OF THE DRAWINGS**

**[0004]** The present invention is illustrated by way of example, and not by way of limitation, in the figures of the accompanying drawings and in which like reference numerals refer to similar elements and in which:

5

**[0005]** **Figure 1** is a block diagram showing portions of a pipeline utilizing flow synonyms in a processor, according to one embodiment.

**[0006]** **Figure 2** is a diagram showing program execution of a program decoded into microcode synonyms, according to one  
10 embodiment.

**[0007]** **Figure 3** is a block diagram showing portions of a pipeline utilizing microcode synonyms in a processor, according to another embodiment of the present disclosure.

**[0008]** **Figure 4** is a diagram showing microcode synonyms occurring  
15 as traces in a trace cache, according to one embodiment of the present disclosure.

**[0009]** **Figure 5** is a flowchart showing a method of utilizing microcode synonyms, according to one embodiment of the present disclosure.

**[0010]** **Figure 6** is a flowchart showing a method of utilizing microcode synonyms, according to another embodiment of the present  
20 disclosure.

**[0011]** **Figures 7A and 7B** are block diagrams of microprocessor systems, according to two embodiments of the present disclosure.

**DETAILED DESCRIPTION**

**[0012]** The following description describes techniques for a processor to use multiple microcode flow synonyms and hardware flow synonyms corresponding to a single instruction, and capable of execution on execution units of differing types. In the following description, numerous specific details such as logic implementations, software module allocation, bus signaling techniques, and details of operation are set forth in order to provide a more thorough understanding of the present invention. It will be appreciated, however, by one skilled in the art that the invention may be practiced without such specific details. In other instances, control structures, gate level circuits and full software instruction sequences have not been shown in detail in order not to obscure the invention. Those of ordinary skill in the art, with the included descriptions, will be able to implement appropriate functionality without undue experimentation. In certain embodiments the invention is disclosed in the form of an Itanium ® Processor Family (IPF) processor or in a Pentium ® family processor such as those produced by Intel ® Corporation. However, the invention may be practiced in other kinds of processors that may wish to use multiple microcode synonyms or hardware synonyms.

**[0013]** Referring now to Figure 1, a diagram showing portions of a pipeline 100 utilizing flow synonyms in a processor is shown, according to one embodiment. The stages of the Figure 1 pipeline 100 are shown for the purpose of discussing the use of flow synonyms in a processor. In other embodiments, the stages of the pipeline may have differing functions and orders. Figure 1 shows a representative collection of execution units in the pipeline 100, with multimedia execution unit

120, branch execution unit 122, integer execution unit 124, floating-point execution unit 126, and memory load/store execution unit 128.

In other embodiments, there may be more than one each of these execution units, and there may be differing types of execution units

5 present.

**[0014]** A fetch stage 104 may fetch or prefetch program instructions from a cache or caches, and supply these instructions to a decode stage 106. The decode stage 106 needs to convert these instructions into a group of simpler instructions called a flow for later execution in the  
10 execution units. Microcode flows may be stored in a microcode read-only-memory (ROM) within decode stage 106. In other embodiments, microcode flows may be stored in non-volatile or writeable memory, such as Flash memory. Hardware flows may be implemented using a set of hardware logic elements within decode stage 106. In a  
15 conventional processor, there would be a one-to-one correspondence between an instruction and its flow, either a microcode flow or a hardware flow. However, in one embodiment of the present disclosure multiple and distinct copies of flows, including microcode flows or hardware flows, may be present for some instructions. If these multiple  
20 and distinct copies of flows for a given instruction produce the same results, they may be called flow synonyms. Flow synonyms may be microcode flow synonyms or hardware flow synonyms each capable of execution on a given type of execution unit, but in many useful cases they will be capable of execution on differing types of execution units.

25 **[0015]** In one embodiment, a pair of flow synonyms, flow synonym 1 110 and flow synonym 2 112, may be included within decode stage 106. In other embodiments, there may be more than two flow synonyms for

an instruction. Each of flow synonym 1 110 and flow synonym 2 112 may be a microcode flow capable of representing a particular instruction, or they may be a hardware flow, or a mix of the two kinds. The decode stage 106 may have logic to select either flow synonym 1 110 or flow synonym 2 112 for decoding the corresponding instruction for subsequent execution depending upon processor status or other rules. The decode stage 106 may examine a status register 118 to determine whether particular execution units are less available or more available. In one embodiment, the status register 118 may be an existing status register required by a scheduler stage 116. The indication of whether a particular execution unit is less available may indicate whether the particular execution unit is currently occupied in execution, or it may indicate that the particular execution unit is powered down as part of a processor reduced power mode. In some cases the status register 118 may indicate soft or hard failures being detected in an execution unit. In any case, the decode stage 106 may select a microcode synonym or a hardware synonym for decoding an instruction when the execution unit utilized by that microcode synonym or hardware synonym is found to be more available. When the status register 118 does not indicate processor reduced power mode or soft or hard failures, the decode stage 106 may take these situations into account by using various selection rules.

**[0016]** In cases where several execution units are more available, decoder stage 106 may need to choose one microcode synonym or hardware synonym from among several corresponding to the several more available execution units. In one embodiment the choosing may be based upon system performance rules. In another embodiment, the

choosing may be based simply upon a default selection basis. In another case where all of the corresponding execution units are less available, then decode stage 106 may have to arbitrate among several microcode synonyms or hardware synonyms based upon rules or history. In one embodiment, the decode stage 106 may determine system performance of various arbitration selections by examining local or global history, in a manner analogous to that performed in branch prediction circuitry. In other embodiments, the arbitration may be performed by a default selection.

10 **[0017]** In another embodiment, decode stage 106 may select more than one microcode synonym or hardware synonym, or even all of the microcode synonyms or hardware synonyms, available for a given instruction, and send them down to the scheduler 116. In one embodiment, let flow synonym S1 110 be a floating-point addition

15 targeted for a floating-point execution unit 126 and let flow synonym S2 112 be a floating-point addition targeted for an integer execution unit 124. Normally flow synonym S1 110 would execute faster than flow synonym S2 112. However, because floating-point execution unit 126 may be heavily occupied in certain circumstances, sometimes S2 112

20 may finish execution first. So in this embodiment, scheduler 116 may schedule both flow synonyms S1 110 and S2 112 for execution on the respective targeted execution units. As only one result should be retired and change processor state, retirement stage 130 may retire whichever flow synonym S1 110 or S2 112 completes execution first. In

25 processors that support predication, retirement stage 130 may then predicate off the slower-executing flow synonym.



**[0018]** In another embodiment, decode stage 106 may again select more than one flow synonym, or all of the flow synonyms, available for a given instruction, and send them down to the scheduler 116. In one embodiment, again let flow synonym S1 110 be a floating-point addition targeted for a floating-point execution unit 126 and let flow synonym S2 112 be a floating-point addition targeted for an integer execution unit 124. In this case scheduler 116 may again schedule both flow synonyms S1 110 and S2 112 for execution on the respective execution units. The utilization of the two flow synonyms S1 110 and S2 112 executing on floating-point execution 126 and integer execution unit 124, respectively, may provide information about soft or hard errors arising by failures in the execution units. So in this embodiment, retirement stage 130 may wait until both flow synonyms complete execution and compare the results. If the results match, then there is no indication of a problem. However, if the results do not match, an exception may be raised and further investigations into the hardware status may be made.

**[0019]** Many if not most instructions may be candidates for having microcode synonyms or hardware synonyms. Numeric calculation instructions, such as integer arithmetic and floating-point arithmetic, may be natural candidates in that they may be performed on differing types of execution units but with differing levels of performance. Even control instructions may be performed on differing types of execution units. For example, a conditional branch instruction may most efficiently be executed on a branch execution unit. However, it is possible to arrange for a branch instruction to be performed by another type of execution unit. For example, a branch instruction could be

executed on an integer execution unit. The integer execution unit could make the conditional determination, and, if the branch should be “not taken” the rest of the microcode could be a no-operation. This would permit the next instruction to be the next instruction sequentially in the program flow. If, however, the branch should be “taken”, then the integer execution unit could be forced to perform an improper execution, such as dividing by zero. This would bring into play an exception handler which could supply the “taken” branch next instruction address.

10 **[0020]** Referring now to Figure 2, a diagram showing program execution of a program decoded into microcode synonyms is shown, according to one embodiment. Let software listing 210 show a progression of microcode flows, including microcode synonyms, as the decode stage decodes a series of instructions. Then let microcode flow

15 212 represent a first instruction. Let a second instruction be represented by two microcode synonyms S1 260 and S2 262, as contained in microcode ROM 252. A conditional determination 214 may be performed by the decode stage to select whether to represent the second instruction by microcode flow 216 corresponding to

20 microcode synonym S1 260, or instead to represent the second instruction by microcode flow 218 corresponding to microcode synonym S2 262. As one example, the conditional determination 214 may be to determine whether the processor has exited from a reduced power mode that powered down the floating-point execution units 255. If so, then a

25 microcode synonym that executes a floating-point instruction on a floating-point execution unit may be selected. If not, and the floating-point execution unit 255 is still powered down, then a microcode

synonym that executes the floating-point instruction on an integer execution unit 254 may be selected. After either microcode flow 216 or 218, a third instruction may be decoded into microcode flow 220.

**[0021]** In one embodiment, the conditional determination 214 may be performed by logic within the decode stage. In another embodiment, the conditional determination 214 may be part of a bundle in microcode ROM 252 that also includes the two microcode synonyms S1 260 and S2 262. In this embodiment, the conditional determination 214 may be changed with updates to the microcode ROM 252 in those cases where microcode ROM 252 is implemented as writable non-volatile memory. Here the conditional determination 214 may be loaded into the decoder stage and performed by circuitry in the decoder stage. In another embodiment, microcode ROM 252 could be replaced by additional circuitry within a decode stage that could implement hardware flow synonyms instead of the microcode synonyms S1 260 and S2 262.

**[0022]** Referring now to Figure 3, a block diagram showing portions of a pipeline 300 utilizing microcode synonyms in a processor is shown, according to another embodiment of the present disclosure. Many of the circuit stage shown in Figure 3 may be similar in function to the equivalent stages shown above in connection with Figure 1. In current processor designs it may be found desirable to have one or more double-precision (or extended precision) floating-point execution units 322. However, considerations of power and integrated circuit die size also may make it desirable to include one or more single-precision floating-point execution units 326. The number of each type may be influenced by statistical analysis of the relative number of single-precision versus double-precision (or extended precision) floating-point

instructions in the kinds of software expected to be executed on the processor. But as these are statistical averages, it may often occur that more or fewer of each type of instruction are executed in a given program.

5 **[0023]** Therefore, in one embodiment, microcode ROM 308 may contain two microcode synonyms for a double-precision floating-point instruction. The microcode synonym S1 310 may be targeted to perform a double-precision floating-point instruction on a double-precision floating-point execution unit 322. The microcode synonym S2  
10 312 may be targeted to perform a double-precision floating-point instruction on a single-precision floating-point execution unit 326. The decode stage 306 may determine which of the two microcode synonyms S1 310, S2 312, to send on to the scheduler stage 316 based upon system performance considerations. In one embodiment, the  
15 determination may be supported by reading system status from a status register 318. For example, when a double-precision floating-point execution unit is more available, then generally the microcode synonym S1 310 may be selected. But when the double-precision floating-point execution unit is less available and a single-precision  
20 floating-point execution unit is more available, then the microcode synonym S2 312 may be selected.

**[0024]** In another embodiment, the microcode synonym S1 310 may be targeted to perform a single-precision floating-point instruction on a single-precision floating-point execution unit 326. The microcode  
25 synonym S2 312 may be targeted to perform a single-precision floating-point instruction on a double-precision floating-point execution unit 322. The decode stage 306 may again determine which of the two

microcode synonyms S1 310, S2 312, to send on to the scheduler stage 316 based upon system performance considerations. In one embodiment, the determination may again be supported by reading system status from a status register 318. For example, when a single-precision floating-point execution unit 326 is more available, then generally the microcode synonym S1 310 may be selected. But when the single-precision floating-point execution unit 326 is less available and a double-precision floating-point execution unit 322 is more available, then the microcode synonym S2 312 may be selected.

10 **[0025]** In other embodiments, there may be a third microcode synonym present in microcode ROM 308. For example, a single-precision floating-point instruction may have microcode synonyms targeted for execution on single-precision floating-point execution units 326, on double-precision floating-point execution units 322, or on integer execution units 324. There may be no particular limit to the number of microcode synonyms for a given instruction. In another embodiment, microcode ROM 308 could be replaced by additional circuitry within a decode stage that could implement hardware flow synonyms instead of the microcode synonyms S1 310 and S2 312.

15 **[0026]** Referring now to Figure 4, a diagram showing microcode synonyms occurring as traces in a trace cache is shown, according to one embodiment of the present disclosure. In the Figure 1 embodiment a buffer stage 114 is shown for the temporary holding of microcode flows, including microcode synonyms, after their issuance from the decode stage 106. Each decoded instruction is used only once, when scheduled, and is thereafter discarded.

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**[0027]** In order to re-use decoded instructions, the trace cache was developed. A trace cache 400 may store the decoded microcode flows as a linked-together “trace” of micro-operations. The trace cache 400 may include several ways (here shown as columns) and sets (here shown as rows). At each intersection of a way and set a micro-operation of the microcode flow may be located, along with a location indicator of the way and set of the next micro-operation in the microcode flow. Examples of traces are shown in Figure 4 as traces 410, 420. Because of the internal linking in the trace, the microcode flow may be easy to retrieve for use. After the original decoding of an instruction into a microcode flow and the construction of the corresponding trace, the trace may be re-used many times whenever the corresponding instruction is scheduled for execution.

**[0028]** Because the traces within a trace cache are left in place for reuse, the decode stage may not be able to issue differing microcode synonyms for each repetition of the instruction. Whichever microcode synonym that is currently instantiated as a trace will simply be re-used. For this reason, in order to utilize differing microcode synonyms in a trace cache the decode stage may need to issue multiple microcode synonyms to the trace cache and have each of them built into a trace. The selection of which trace, corresponding to the selection of which microcode synonym, to use at a particular instance of an instruction may need to be performed in circuitry of the trace cache rather than in the decode stage. Similarly, when the trace cache needs to eject the flows corresponding to a given instruction, the trace cache may need to be capable of ejecting all the microcode synonyms resident within the trace cache.

**[0029]** Referring now to Figure 5, a flowchart showing a method 500 of utilizing flow synonyms is shown, according to one embodiment of the present disclosure. Although microcode flow synonyms are discussed in the Figure 5 flowchart, in other embodiments hardware flow synonyms may be used. An instruction may enter the decision block 510, where it may be determined whether microcode flow synonyms exist for that instruction. If not, then method 500 exits decision block 510 via the NO path and the single microcode flow is decoded in decode block 522. However, if two or more microcode flow synonyms exist for the instruction, then the method exits decision block 510 via the YES path and the status of the execution units may be checked in block 512.

**[0030]** Then in decision block 516 it may be determined whether there is a clear status on one or more of the execution units targeted by the microcode flow synonyms. In one embodiment, "clear status" may indicate that an execution unit is more available. If not, then the method exits decision block 516 via the NO path and in block 520 an arbitration is made to select a microcode flow synonym. That microcode flow synonym is then sent on to the decode block 522. If so, then the method exits decision block 516 via the YES path and in block 518 a microcode flow synonym is chosen. If only one execution unit is more available, then the microcode flow synonym targeted for that execution unit may be selected. If more than one execution unit is more available, then a microcode flow synonym targeted for one of the more available execution units may be selected by other rules, such as a default selection. In any case, then the decode block 522 decodes the instruction using the microcode flow synonym.

**[0031]** Upon leaving the decode block 522, the method then may schedule the microcode flow synonym in schedule block 524 prior to execution on the targeted execution unit in execute block 526. The results of the execution may then be retired in retirement block 528.

5 **[0032]** Referring now to Figure 6, a flowchart showing a method 600 of utilizing flow synonyms is shown, according to another embodiment of the present disclosure. Although microcode flow synonyms are discussed in the Figure 6 flowchart, in other embodiments hardware flow synonyms may be used. An instruction may enter the decision  
10 block 610, where it may be determined whether microcode flow synonyms exist for that instruction. If not, then method 600 exits decision block 610 via the NO path and the single microcode flow is treated conventionally in blocks 620 through 626. However, if two or more microcode flow synonyms exist for the instruction, then the  
15 method exits decision block 610 via the YES path.

**[0033]** In block 612, the decoder may issue two or more microcode flow synonyms for the instruction under consideration. Then in block 614 these two or more microcode flow synonyms may be scheduled for execution when the targeted execution units are more available. These  
20 execution units then execute, in block 616, the corresponding microcode flow synonyms. The retirement stage may, in block 618, take the results of the first microcode flow synonym to complete execution and retire those results. In other embodiments, the retirement stage may permit all the microcode flow synonyms to complete and compare  
25 the results before retirement. If some of the results do not match, then the retirement stage may raise an exception indicating hard or soft errors in the processor.



**[0034]** Referring now to Figures 7A and 7B, schematic diagrams of systems including a processor supporting execution of flow synonyms are shown, according to two embodiments of the present disclosure.

The Figure 7A system generally shows a system where processors, memory, and input/output devices are interconnected by a system bus, whereas the Figure 7B system generally shows a system where processors, memory, and input/output devices are interconnected by a number of point-to-point interfaces.

**[0035]** The Figure 7A system may include several processors, of which only two, processors 40, 60 are shown for clarity. Processors 40, 60 may include level one caches 42, 62. The Figure 7A system may have several functions connected via bus interfaces 44, 64, 12, 8 with a system bus 6. In one embodiment, system bus 6 may be the front side bus (FSB) utilized with Pentium® class microprocessors manufactured by Intel® Corporation. In other embodiments, other busses may be used. In some embodiments memory controller 34 and bus bridge 32 may collectively be referred to as a chipset. In some embodiments, functions of a chipset may be divided among physical chips differently than as shown in the Figure 7A embodiment.

**[0036]** Memory controller 34 may permit processors 40, 60 to read and write from system memory 10 and from a basic input/output system (BIOS) erasable programmable read-only memory (EPROM) 36. In some embodiments BIOS EPROM 36 may utilize flash memory. Memory controller 34 may include a bus interface 8 to permit memory read and write data to be carried to and from bus agents on system bus 6. Memory controller 34 may also connect with a high-performance graphics circuit 38 across a high-performance graphics interface 39. In

certain embodiments the high-performance graphics interface 39 may be an advanced graphics port AGP interface. Memory controller 34 may direct read data from system memory 10 to the high-performance graphics circuit 38 across high-performance graphics interface 39.

- 5   **[0037]**   The Figure 7B system may also include several processors, of which only two, processors 70, 80 are shown for clarity. Processors 70, 80 may each include a local memory channel hub (MCH) 72, 82 to connect with memory 2, 4. Processors 70, 80 may exchange data via a point-to-point interface 50 using point-to-point interface circuits 78, 88.
- 10   Processors 70, 80 may each exchange data with a chipset 90 via individual point-to-point interfaces 52, 54 using point to point interface circuits 76, 94, 86, 98. Chipset 90 may also exchange data with a high-performance graphics circuit 38 via a high-performance graphics interface 92.
- 15   **[0038]**   In the Figure 7A system, bus bridge 32 may permit data exchanges between system bus 6 and bus 16, which may in some embodiments be a industry standard architecture (ISA) bus or a peripheral component interconnect (PCI) bus. In the Figure 7B system, chipset 90 may exchange data with a bus 16 via a bus interface 96. In
- 20   either system, there may be various input/output I/O devices 14 on the bus 16, including in some embodiments low performance graphics controllers, video controllers, and networking controllers. Another bus bridge 18 may in some embodiments be used to permit data exchanges between bus 16 and bus 20. Bus 20 may in some embodiments be a
- 25   small computer system interface (SCSI) bus, an integrated drive electronics (IDE) bus, or a universal serial bus (USB) bus. Additional I/O devices may be connected with bus 20. These may include

keyboard and cursor control devices 22, including mice, audio I/O 24, communications devices 26, including modems and network interfaces, and data storage devices 28. Software code 30 may be stored on data storage device 28. In some embodiments, data storage device 28 may  
5 be a fixed magnetic disk, a floppy disk drive, an optical disk drive, a magneto-optical disk drive, a magnetic tape, or non-volatile memory including flash memory.

**[0039]** In the foregoing specification, the invention has been described with reference to specific exemplary embodiments thereof. It will,  
10 however, be evident that various modifications and changes may be made thereto without departing from the broader spirit and scope of the invention as set forth in the appended claims. The specification and drawings are, accordingly, to be regarded in an illustrative rather than a restrictive sense.